# Implications of Cohesion for Binary Asteroid Formation

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- \* Gravitational aggregates
- \* The code
- \* Cohesionless models
- \* Rigid models
- \* Models with variable cohesion
- \* The future

# Gravitational Aggregates



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### Gravitational Aggregates

\* ...are bodies made up of multiple components and having low relative tensile strength (RTS).
\* RTS = (body tensile strength)/(component strength).
\* Zero RTS → rubble pile.

- \* Gravity dominates over material strength.
- May still have shear strength.
  \* Ability to hold non-ideal-fluid-equilibrium shape.
- \* Growing evidence for gravitational aggregates.

# Modeling Gravitational Aggregates

- \* Ingredients:
  - \* Gravity.
  - \* Collisions (with adjustable dissipation).
  - \* Component shape effects (shear strength).
  - \* Variable cohesion.

### The Code: pkdgrav

- \* N-body code that treats gravity and collisions between spheres (or collections of spheres).
- Solves equations of motion for point masses using second-order leapfrog integrator:

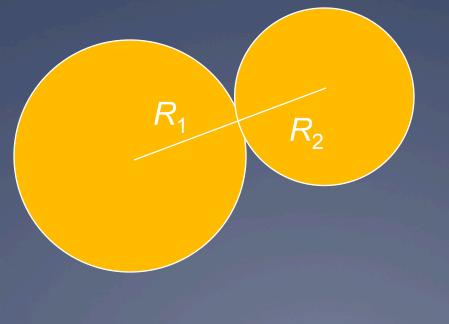
$$\ddot{\mathbf{r}}_{i} = -\sum_{j \neq i} \frac{Gm_{j}(\mathbf{r}_{i} - \mathbf{r}_{j})}{\left|\mathbf{r}_{i} - \mathbf{r}_{j}\right|^{3}}$$

### Code Details

- \* Based on cosmological code developed by Joachim Stadel and Tom Quinn.
- Uses modified k-d tree algorithm (with expansions to hexadecapole) to speed up calculations.
  Reduces force cost to O(N log N).
  - \* Introduces small errors (<< 1%) in force calculation.
- Exploits parallelization to distribute work among available cores.
  - \* Linear scaling up to hundreds of cores.

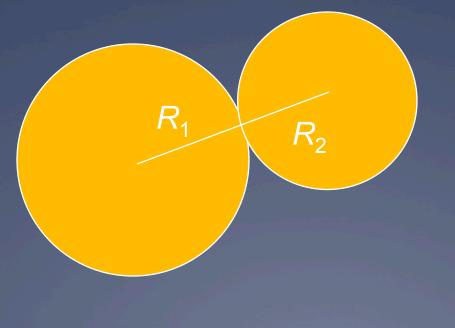
## **Collision Detection**

- \* Particles collide when separation distance equals sum of radii.
  - \* Collisions predicted in advance during integration.
  - \* Uses nearest-neighbor search tree.



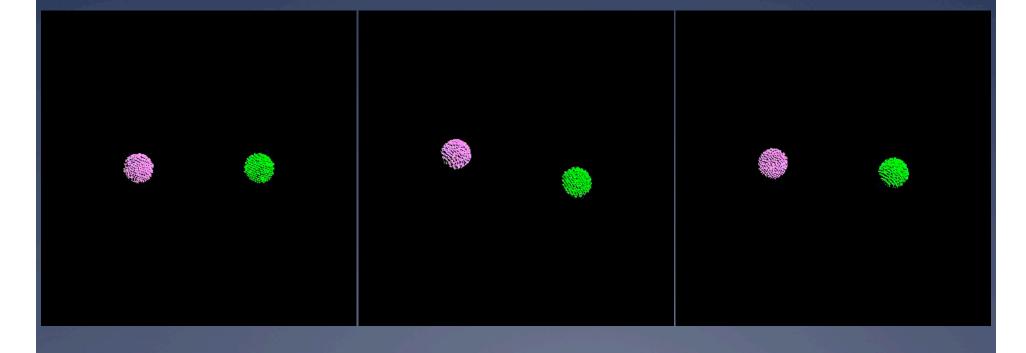
## **Collision Resolution**

- \* Post-impact speed(s) and/or body spin(s) set by sticking/bouncing/splitting rules.
  - \* Bouncing parameterized by coefficient of restitution (normal & tangential).

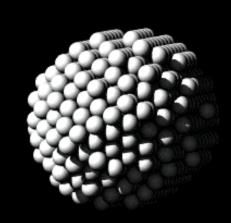


- \* Idealized rubble piles (perfect, solid spheres; bouncing, no sticking or splitting).
- \* Many uses. Basic assumption: gravity more important than material properties.

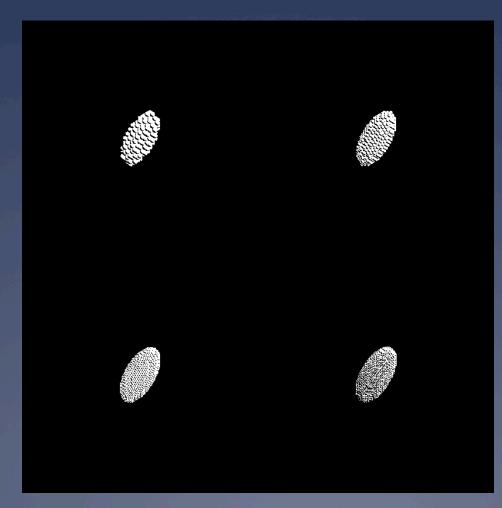
#### Rubble pile collisions



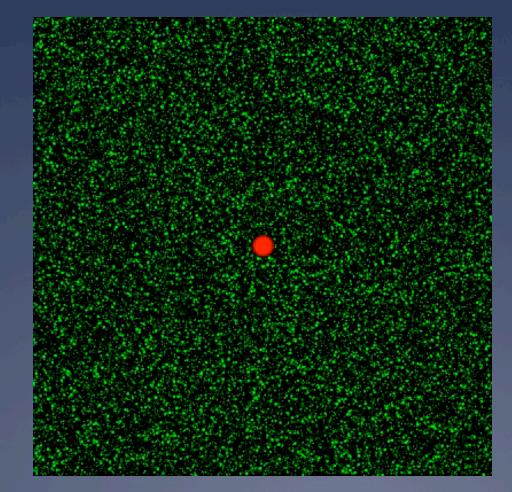
#### **Tidal disruption**



#### Effect of resolution



#### Planetary rings



# Shear Strength

\* Rubble piles do not require cohesion to retain non-equilibrium shapes.

\* Finite particle effects provide shear strength.

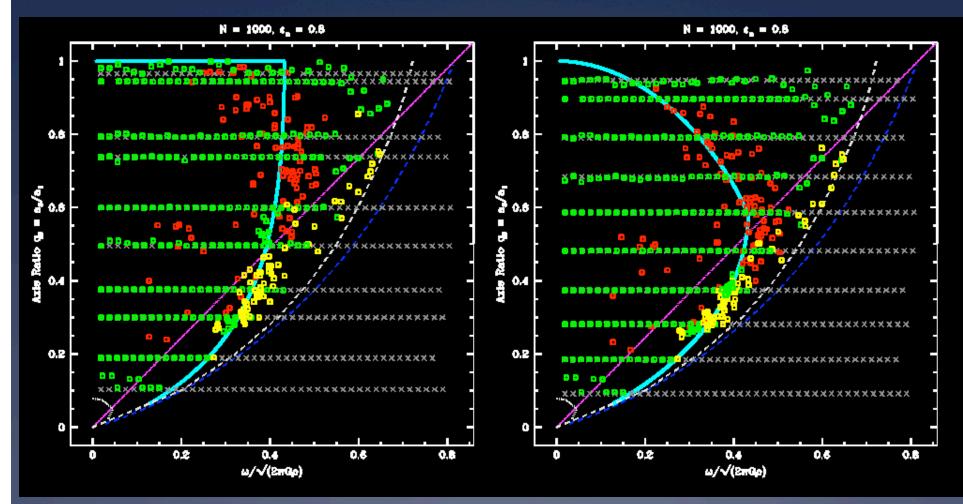
# Shear Strength

#### Rubble cubes colliding



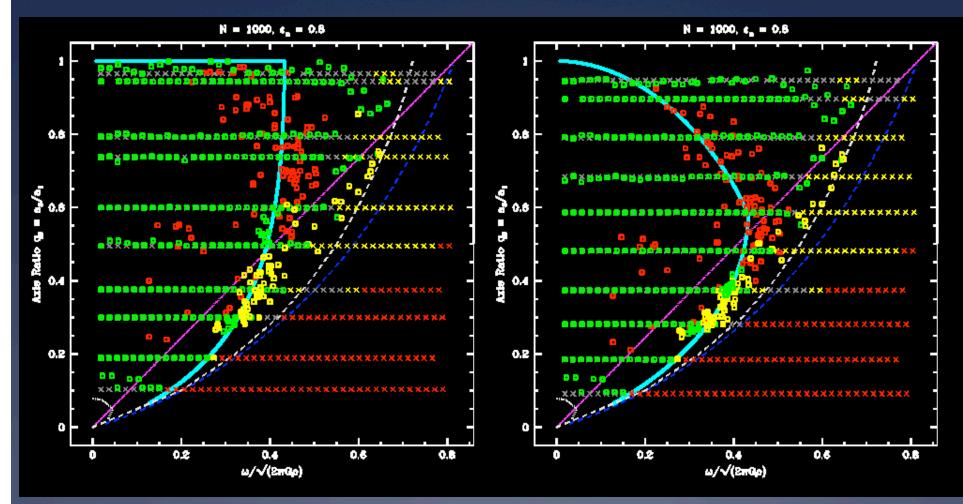


#### Rubble Pile Equilibrium Shapes



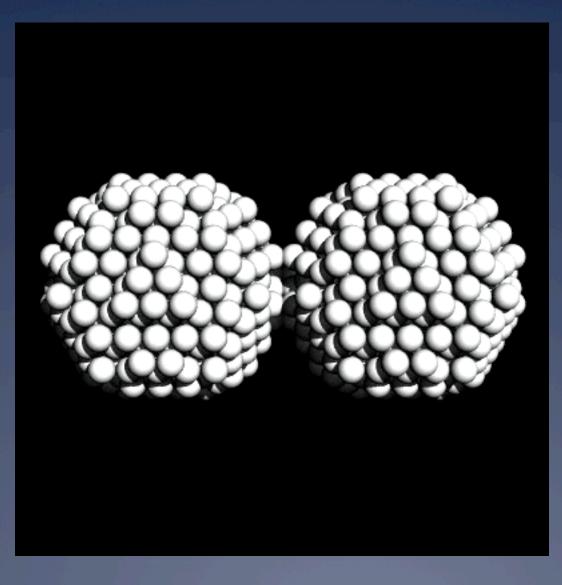
Mass loss: 0% < 10% > 10% X = initial condition

#### Rubble Pile Equilibrium Shapes



Mass loss: 0% < 10% > 10% X = initial condition

# **Rubble Fission**



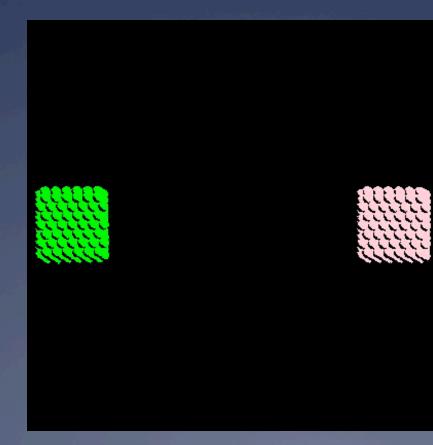
- \* Can "fuse" spheres together to form more complex shapes.
- Either as an initial condition, or as a sticking rule (v<sub>impact</sub> < v<sub>stick</sub>).
- Need to solve Euler's equations of rigid-body motion with external torques.
   \* Use 5<sup>th</sup>-order (time adaptive) Runge-Kutta.

$$I_{1}\dot{\omega}_{1} - \omega_{2}\omega_{3}(I_{2} - I_{3}) = N_{1}$$
$$I_{2}\dot{\omega}_{2} - \omega_{3}\omega_{1}(I_{3} - I_{1}) = N_{2}$$
$$I_{3}\dot{\omega}_{3} - \omega_{1}\omega_{2}(I_{1} - I_{2}) = N_{3}$$

$$\dot{\hat{\mathbf{p}}}_1 = \omega_3 \hat{\mathbf{p}}_2 - \omega_2 \hat{\mathbf{p}}_3$$
$$\dot{\hat{\mathbf{p}}}_2 = \omega_1 \hat{\mathbf{p}}_3 - \omega_3 \hat{\mathbf{p}}_1$$
$$\dot{\hat{\mathbf{p}}}_3 = \omega_2 \hat{\mathbf{p}}_1 - \omega_1 \hat{\mathbf{p}}_2$$

- \* Collision detection and resolution considerably more complicated.
- Predict time to collision between spheres on rotating aggregates. Only an approximation.
- Solve outcome using method of generalized coefficients for non-central impacts.
   \* Surface friction not supported.

Rigid cubes colliding



Rigid bodies torquing





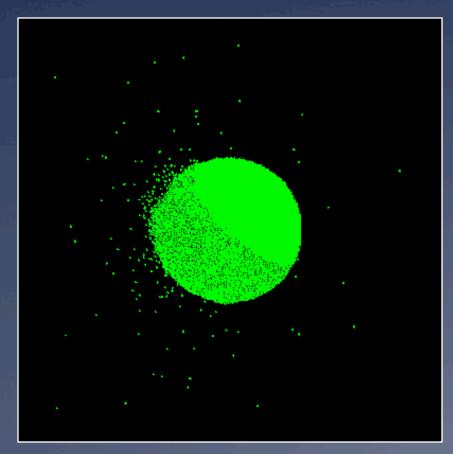
#### \* Specify either...

- 1. ...size-dependent strength (and optional splitting threshold,  $v_{impact} > v_{split}$ ) with only rigid failure;
- 2. or, Young's modulus and maximum strain to simulate elastic failure.

\* In case 1 (rigid failure), strength  $S \sim R^{\alpha}$ , and stress arises from rotation and tides.

#### \* Implementation:

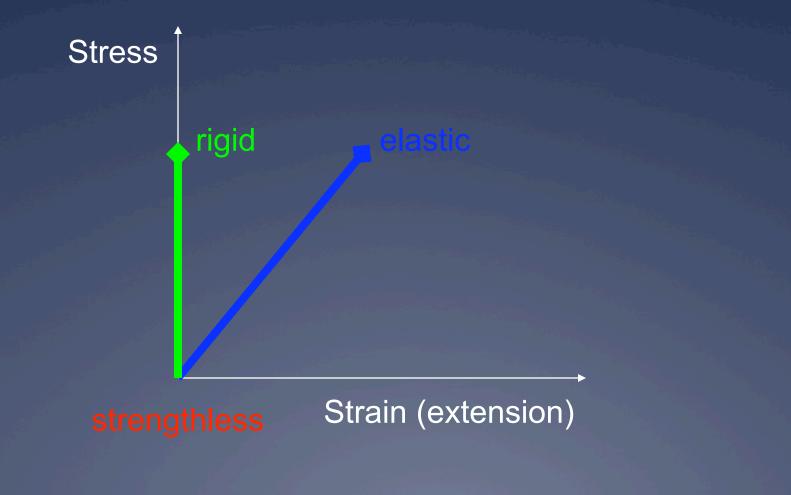
- \* Compare acceleration acting on constituent particle relative to center of mass with strength multiplied by  $\pi R^2 / m$ .
- Particles experiencing excessive stress are liberated (but may stick again later, if desired).



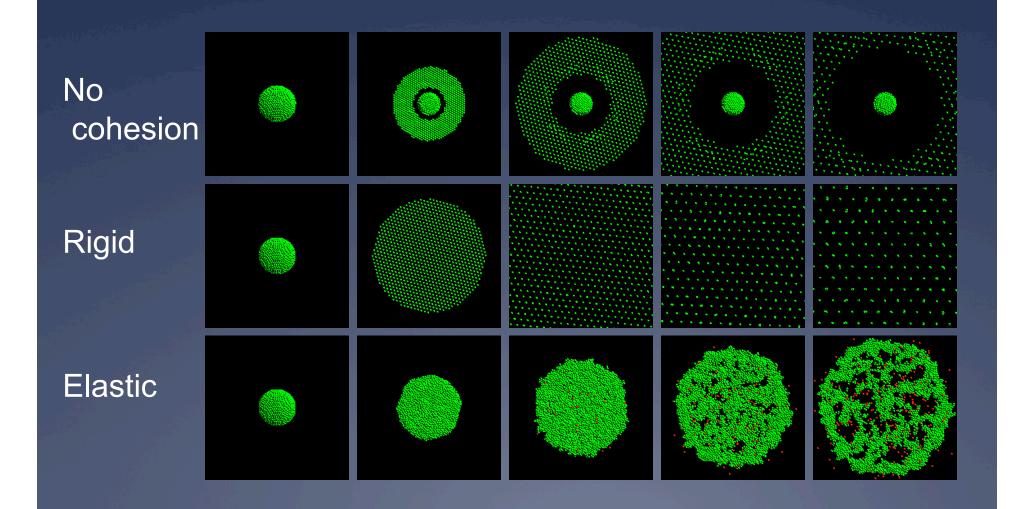
Post-catastrophic disruption gravitational reaccumulation with sticking, bouncing, splitting, and strength.

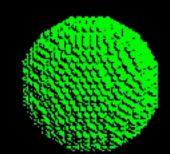
- In case 2 (elastic failure), particles can move with respect to one another, up to a maximum displacement (strain).
- \* Implementation:
  - Particles must be free to move, so Euler's equations not used.
  - \* Add restoring force between neighboring particles proportional to strain (= Young's modulus × stress).
  - \* If maximum strain exceeded, particle permanently liberated (all particles start at close to zero strain).

# Stress-strain Curve

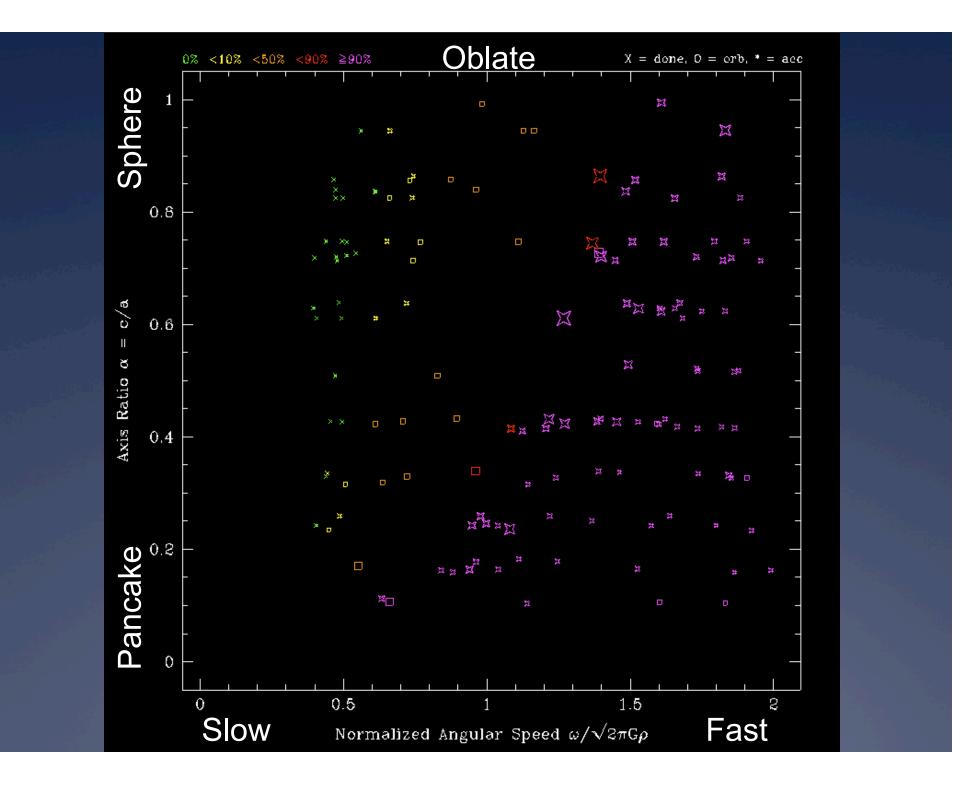


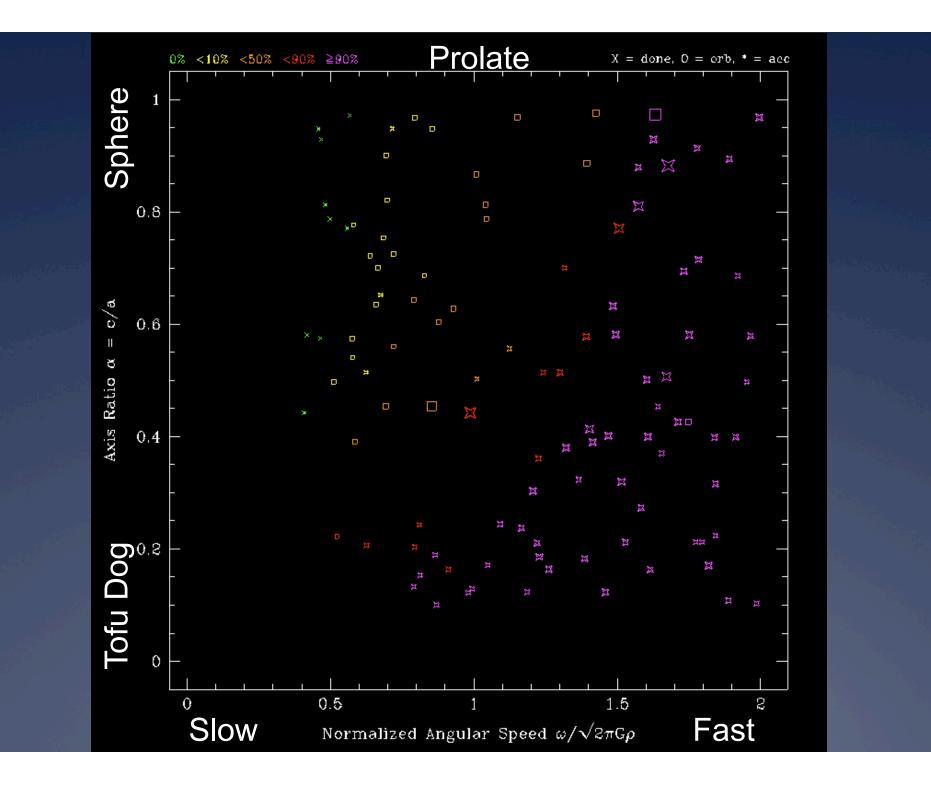
# Response to Excessive Spin

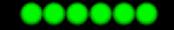


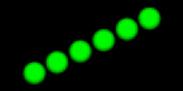


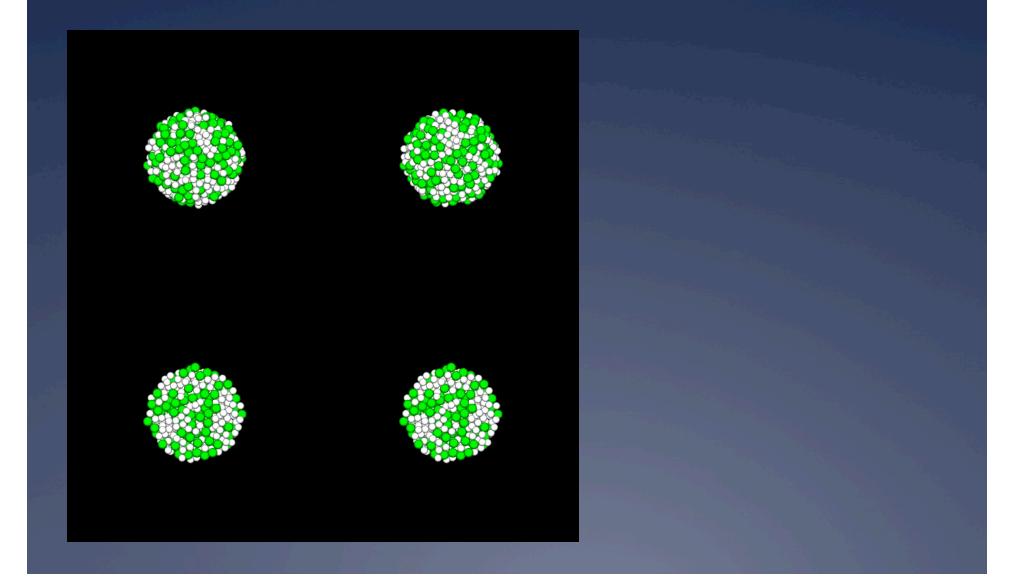
Elastic strain model at very high initial spin.

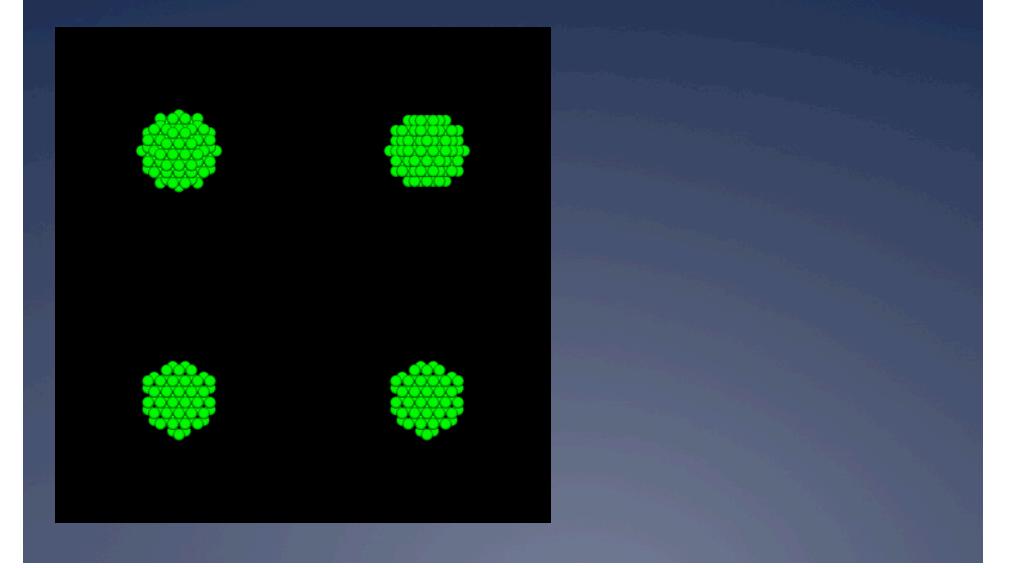












#### The Future

- Investigate effect of particle size/shape on gravitational aggregate dynamics (see next talk!).
- \* Compare strength models with Holsapple.
- Express strain relative to initial lattice for elastic models.
- Implement particle memory for modeling weak points, cracks, etc.

# Extra Slides...

# Van der Waals Force

