Average time-variable gravity from GPS orbits of recent geodetic satellites



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Average time-variable gravity from GPS orbits: Contents

- Overview of our inversion method
- Time series tools: PACF, AR
- Results using real data (CHAMP, GRACE A/B, GOCE)
 - Static & time-variable solutions
 - Geocentre motion from GPS orbits

Gravity field from orbit: acceleration approach

SST:high-low (CHAMP, GRACE, GOCE)

- long time series of positions with constant time step
- Positions r_{gps}(t) → by numerical derivative we obtain observations: "GPS-based accelerations" a_{GPS}
- <u>Newton second law</u>: $\mathbf{a}_{GPS} \approx d^2 \mathbf{r}/dt^2 = \mathbf{a}_{geop} + \mathbf{a}_{LS} + \mathbf{a}_{TID} + \mathbf{a}_{NG}$

a_{geop}(r) ≡ ∑ GC×∇SSH(r,θ,φ) … geopotential in spherical harmonics SSH, GC…geopotential coefficients
 a_{LS}, a_{TID}, a_{NG} …lunisolar, tides, nongravitational



■ Newton law → linear system:

$$\sum \mathbf{GC} \times \nabla SSH(\mathbf{r}, \theta, \varphi) + \boldsymbol{\varepsilon} = \mathbf{a}_{GPS} - (\mathbf{a}_{LS} + \mathbf{a}_{TID} + \mathbf{a}_{NG})$$
(*)

Now geopotential coefficients (GC) can be solved for using (*).

Acceleration approach: ASU¹ version

Linear system of observation equations to estimate **geopotential coefficients GC**: $\sum \mathbf{GC} \times \nabla SSH(r,\theta,\phi) + \boldsymbol{\varepsilon} = \mathbf{a}_{GPS} - (\mathbf{a}_{LS} + \mathbf{a}_{TID} + \mathbf{a}_{NG})$

Solution method:

- Polynomial smoothing filters: positions $\mathbf{r}_{gps}(t) \rightarrow GPS$ -based acceleration $\mathbf{a}_{GPS} \equiv d^2Q(\mathbf{r}_{gps})/dt^2$
- Assumption: uncertainty in a_{LS}, a_{TID}, a_{NG} is negligible relative to that of a_{GPS}
- Problem: Numerical derivative amplifies noise in GPS positions
 - Solution: Generalized least squares (GLS)
 - \rightarrow linear transformation of system (*)
- Problem: Real data → GPS positions have correlated errors
 - Solution: partial autocorrelation function (PACF) → autoregressive model (AR)
 - \rightarrow linear transformation of system (*)

Solving transformed system (*) we get geopotential coefficients GC by ordinary least squares

- no a priori gravity field model
- no regularization
- ¹ASU...Astronomical Institute ASCR

(*)

Decorrelation of GPS position errors using AR process

Problem: Real GPS positions have correlated errors

- Indicated by sample autocorrelation function ACF
 - ➤Unrealistic error bars
 - Possibly biased parameter estimates

Partial autocorrelation function PACF

Rapid decay of PACF \rightarrow suitability of AR model to represent the correlation structure

 In figure, fitted autoregressive model AR of order 4 approximates ACF of residuals

Decorrelation of residuals using fitted AR models

- by linear transformation of linear system (*)
- ACF and PACF become approx. delta functions

Estimation of geopotential coefficients GC

- After decorrelation, GC are more accurate by factor 2–3!
- More realistic uncertainty estimate of GC







Static gravity field models (CHAMP, GRACE, GOCE)

Examples of successful application of the presented inversion method to estimate geopotential coefficients.

One-day solutions

CHAMP yearly solution for 2003



CHAMP and GRACE A/B solutions (2003–2009)



Time-variable gravity from GPS orbits (GRACE, CHAMP)

- CHAMP, GRACE A/B kinematic orbits (2003–2009)
- monthly solutions estimated up to degree 20
- to reduce aliasing due to truncation error

 → we subtract signal from suitable static geopotential model for degrees 21–100 (e.g. EGM2008)

Monthly solutions to degree 10 used in time series model: ≻ mean, trend, seasonal sinusoid

Figures: Seasonal gravity, average October variation

- (a) from GRACE microwave ranging (KBR)
- (b)–(c) time-variable gravity from GPS tracking
 - > most important continental areas with seasonal hydrology
 - ➤ noisier compared to KBR solutions
 - > spatial resolution smaller than KBR solutions









Geocentre motion from GPS orbits (GRACE A/B)

- In our monthly solutions, we fitted also degree-one geopotential coefficients C₁₀, C₁₁, S₁₁
- Usually they are identically <u>zero</u> ↔ origin of coordinate system at <u>centre of mass (CM)</u>
- If fitted, they may show motion of CM relative to centre of Earth figure (e.g. ITRF):

 $G_x = \sqrt{3} R C_{11}$ $G_y = \sqrt{3} R S_{11}$ $G_z = \sqrt{3} R C_{10}$

Kang et al. (2009) found geocentre motion from GPS tracking using GRACE KBR fields

Figure: Annual cycle in geocentre motion (2005–2009)

- 3- σ confidence intervals for amplitudes and phases
 - ➤all the results are rather <u>noisy</u>
 - ➤order-of-magnitude agreement
 - ➢ probable existence of annual systematic variation



SLR: Cheng et al. (2010), <u>ftp://ftp.csr.utexas.edu/pub/slr/geocenter/</u> Rie: Rietbroek et al. (2012), <u>http://igg.uni-bonn.de/apmg/index.php?id=geozentrum</u> Swe: Swenson et al. (2008), <u>ftp://podaac.jpl.nasa.gov/allData/tellus/L2/degree 1/</u> GA, GB: our fits to GRACE A/B monthlies, <u>http://www.asu.cas.cz/bezdek/vyzkum/geopotencial/</u>

Time-variable gravity from GPS orbits (GOCE)

- GOCE kinematic orbits (2009–2012)
- monthlies estimated to degree 20
- aliasing from degrees 21–120 reduced by time-wise GOCE model (Release 4)
- time series model: monthlies up to degree 10

Figure: Time variable gravity in Amazonia

- agreement in seasonal component
- mean & trend different: short time span

Figure: Seasonal gravity variation

- important continental hydrology areas
- noisier compared to KBR solutions
- spatial resolution smaller than KBR
- first GOCE-only time-variable gravity





Average time-variable gravity from GPS orbits: Conclusions

- Well identified continental areas with pronounced seasonal hydrology variation
- Much reduced spatial resolution vs. GRACE KBR monthly solutions
- Advantages:
 - ➢ possibly many satellite missions equipped with GPS
 - > independent source of information on time-variable gravity

Website: http://www.asu.cas.cz/~bezdek/

- long-term geopotential solutions (CHAMP, GRACE)
- their full covariance matrices
- computational details (preprint, under review)
- free Matlab package for 2D/3D visualising







Thank you for your attention